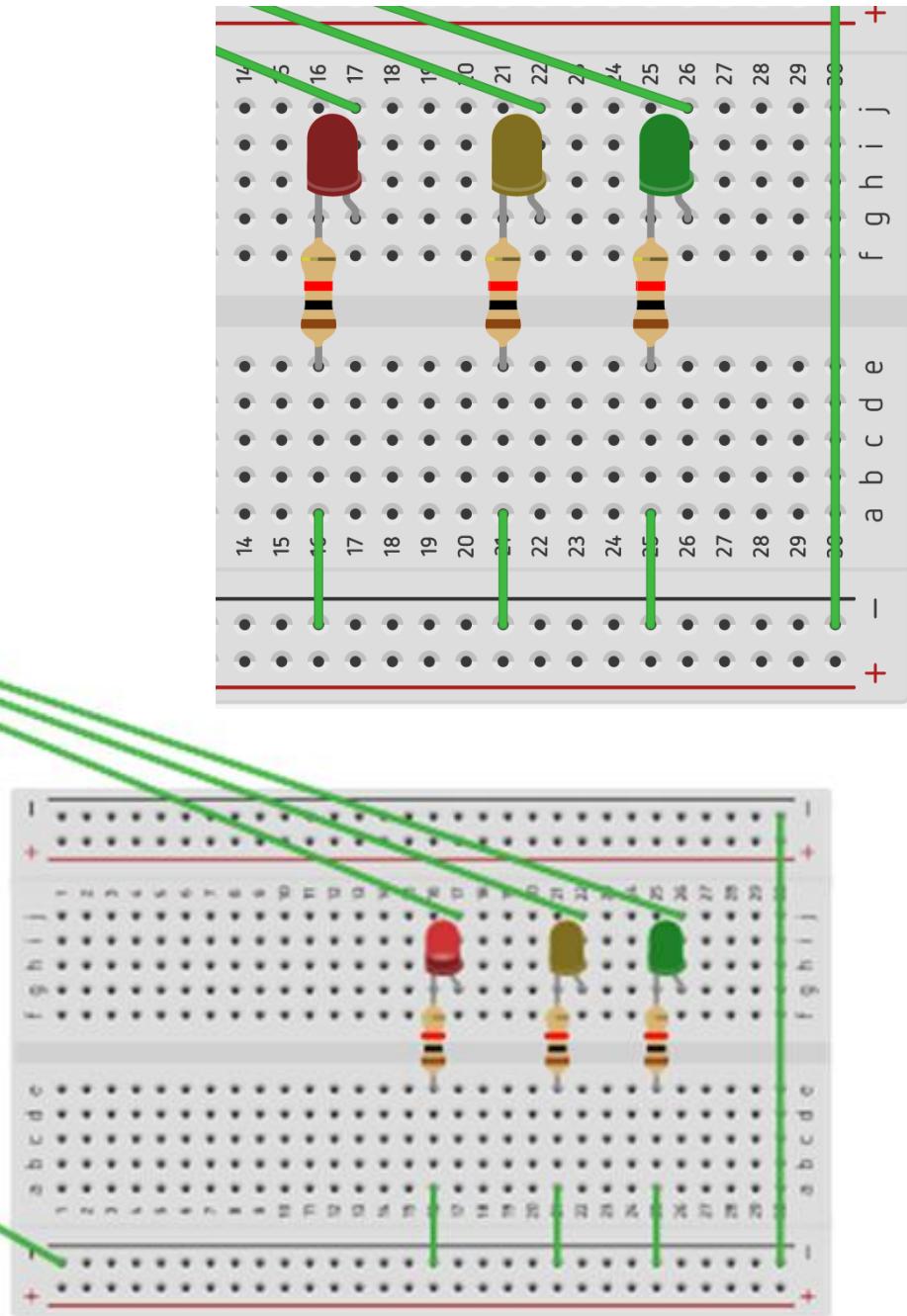
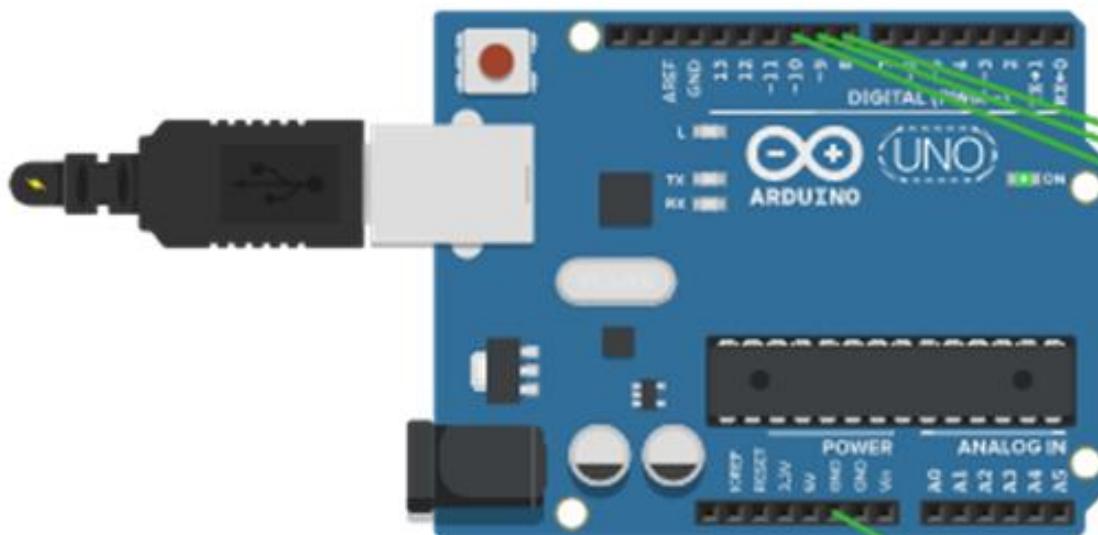


CIRCUITI ELETTRICI CON ARDUINO



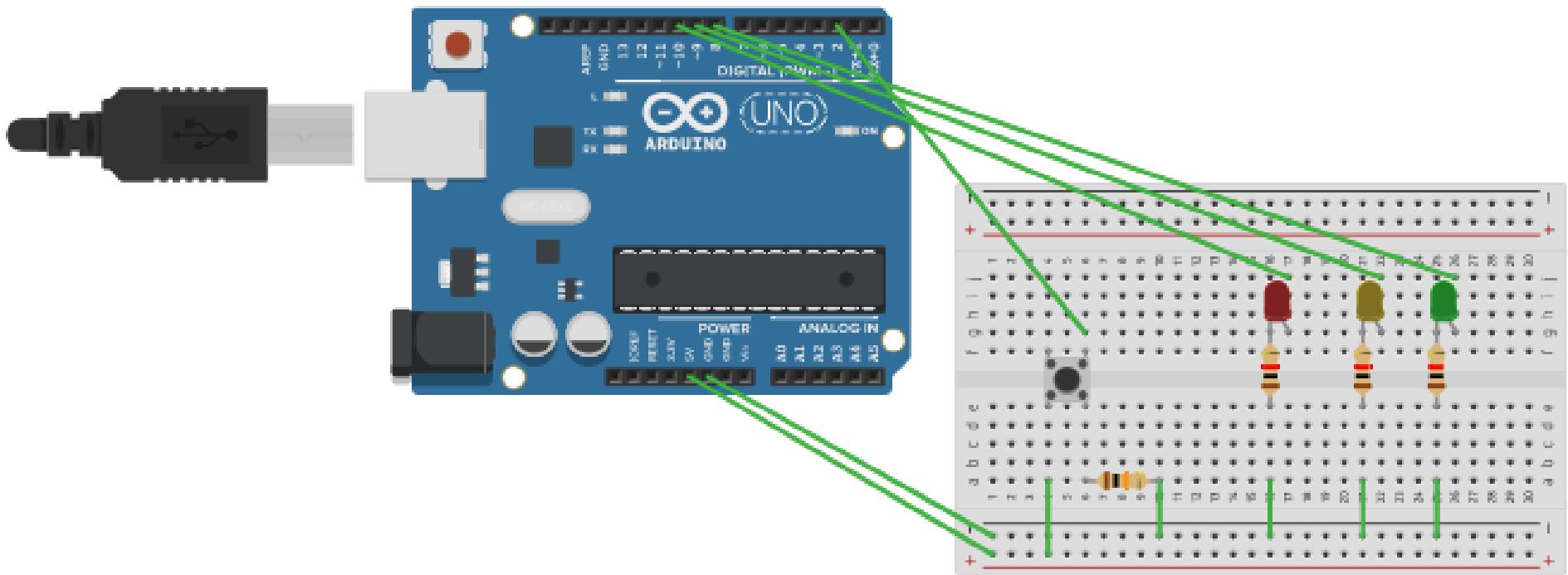
```
int ledRosso = 10;
int ledGiallo = 9;
int ledVerde = 8;

// the setup routine runs once when you press reset:
void setup() {
    // initialize the digital pin as an output.
    pinMode(ledRosso, OUTPUT);
    pinMode(ledGiallo, OUTPUT);
    pinMode(ledVerde, OUTPUT);
}

// the loop routine runs over and over again forever:
void loop() {
    digitalWrite(ledRosso, HIGH);
    delay(1000);          // wait for a second
    digitalWrite(ledGiallo, HIGH);
    delay(1000);          // wait for a second
    digitalWrite(ledVerde, HIGH);
    delay(1000);          // wait for a second

    digitalWrite(ledVerde, LOW);
    delay(1000);          // wait for a second
    digitalWrite(ledGiallo, LOW);
    delay(1000);          // wait for a second
    digitalWrite(ledRosso, LOW);
    delay(1000);          // wait for a second

}
```



```
int ledRosso = 10;
int ledGiallo = 9;
int ledVerde = 8;
const int buttonPin = 2; // the number of the pushbutton pin
// variables will change:
int buttonState = 0; // variable for reading the pushbutton status
```

// the setup routine runs once when you press reset:

```
void setup() {
    // initialize the digital pin as an output.
    pinMode(ledRosso, OUTPUT);
    pinMode(ledGiallo, OUTPUT);
    pinMode(ledVerde, OUTPUT);
    pinMode(buttonPin, INPUT);
}
```

// the loop routine runs over and over again forever:

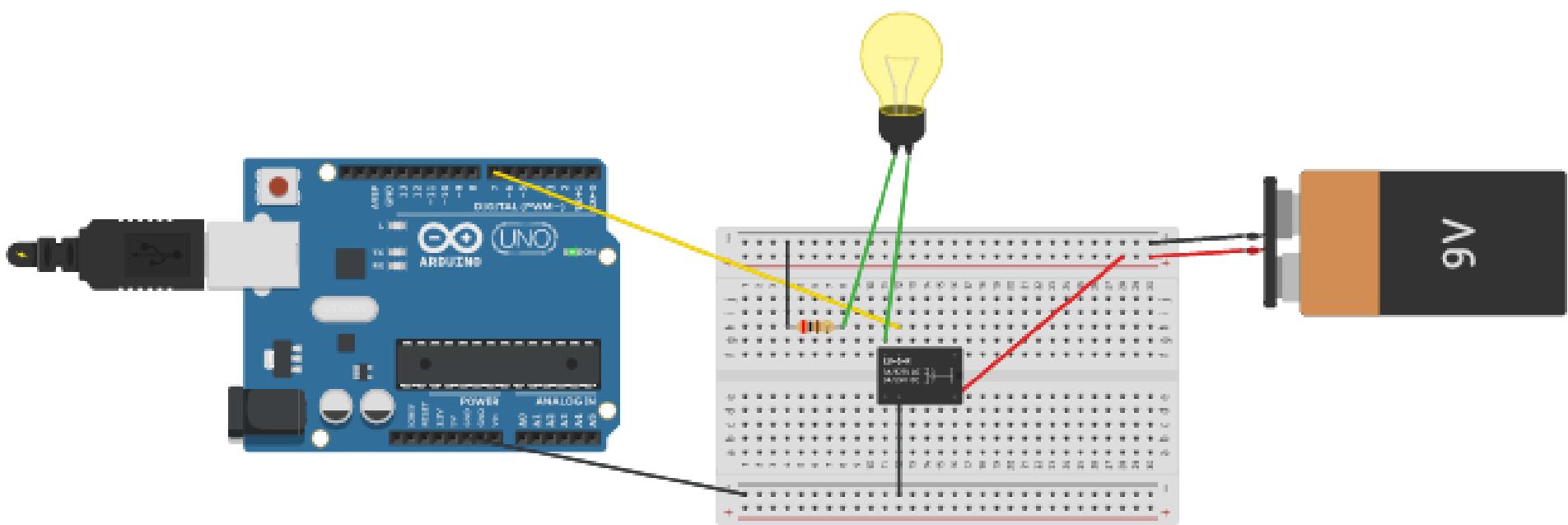
```
void loop() {
    // read the state of the pushbutton value:
    buttonState = digitalRead(buttonPin);

    // check if the pushbutton is pressed. If it is, the buttonState is HIGH:
    if (buttonState == HIGH) {
        digitalWrite(ledRosso, HIGH);
        delay(1000); // wait for a second
        digitalWrite(ledGiallo, HIGH);
        delay(1000); // wait for a second
        digitalWrite(ledVerde, HIGH);
        delay(1000); // wait for a second
    }
}
```

```
digitalWrite(ledVerde, LOW); // turn the LED on (HIGH is the voltage level)
delay(1000); // wait for a second
digitalWrite(ledGiallo, LOW); // turn the LED off by making the voltage LOW
delay(1000); // wait for a second
digitalWrite(ledRosso, LOW); // turn the LED off by making the voltage LOW
delay(1000); // wait for a second
} else {
```

```
}
```

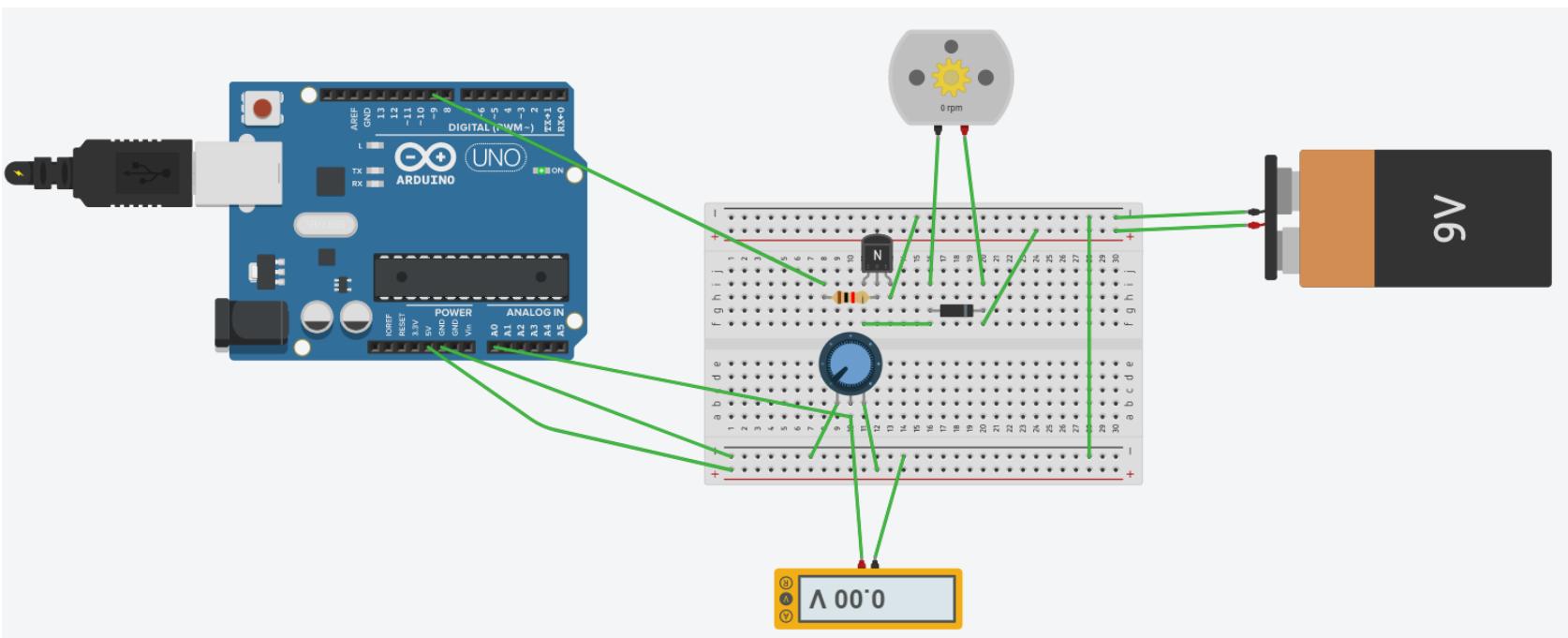
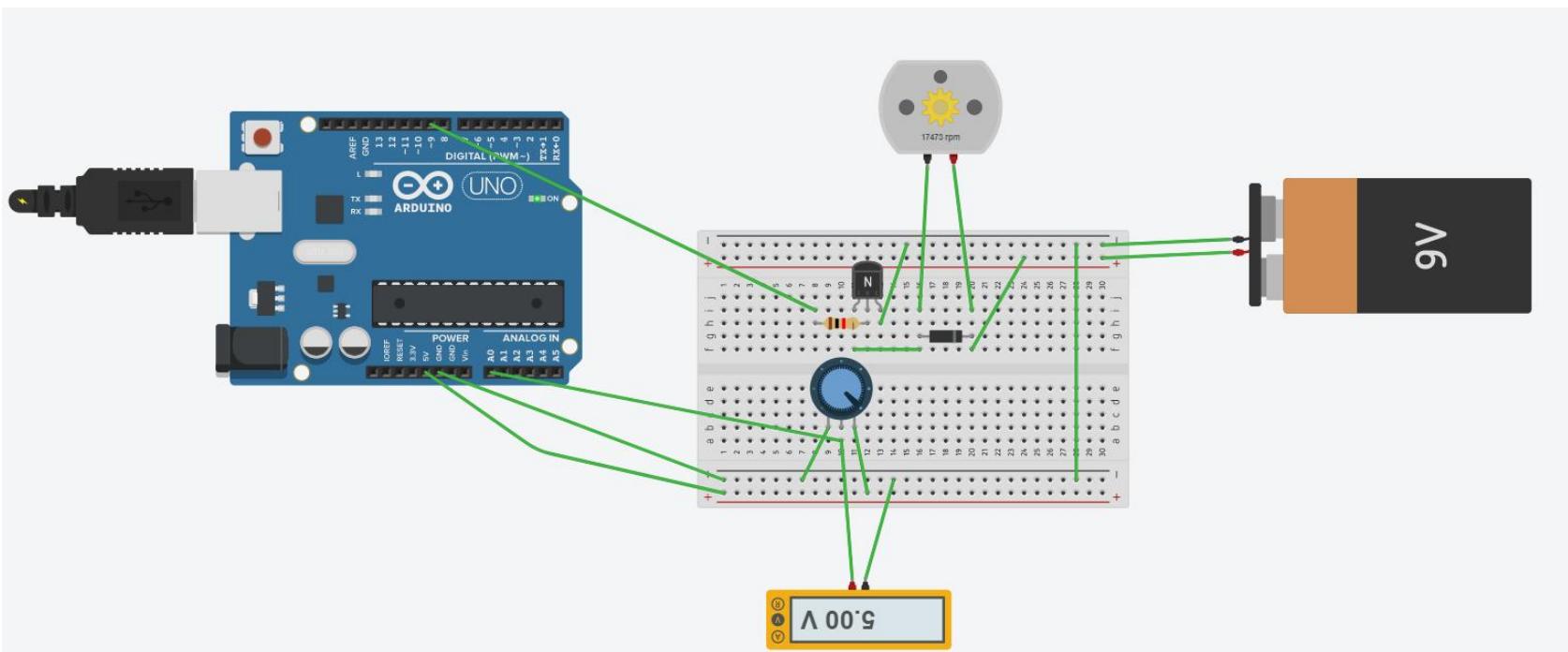
```
}
```



```
int relePin = 7;

// the setup routine runs once when you press reset:
void setup() {
  // initialize the digital pin as an output.
  pinMode(relePin, OUTPUT);
}

// the loop routine runs over and over again forever:
void loop() {
  digitalWrite(relePin, HIGH);
  delay(2000);      // wait for 2 second
  digitalWrite(relePin, LOW);
  delay(2000);      // wait for 2 second
}
```



```
const int potenziometro = 0; // pin del potenziometro  
const int motore = 9; // pin del motore
```

```
void setup() {  
    // inizializza il motore come output  
    pinMode(motore, OUTPUT);  
}
```

```
void loop(){  
    // Riporta il valore analogico da 0-1023 a 0-255  
    byte valore = map(analogRead(potenziometro),0,1023,0,255);  
  
    // Il motore gira con velocità proporzionale alla rotazione del potenziometro  
    analogWrite(motore,valore);  
}
```

